



**when program starts**



set movement motors to

A+B ▼



set 1 motor rotation to

17.5

cm ▼

moved



set movement speed to

50

%





move

right: 100

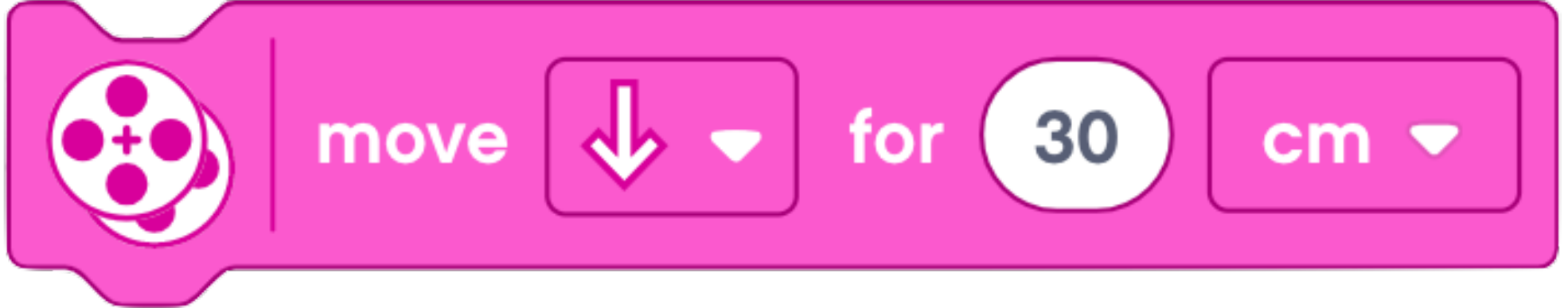
for

0.4

rotations











move

right: 100

for

0.4

rotations



